November 9 (Day 1)			November 10 (Day 2)				
Session	JST	CET	EST	Session	JST	СЕТ	EST
Opening Session				Dynamic Map			
Regional Activities	9:00-10:40	1:00-2:40	#19:00-#20:40		9:00-10:30	1:00-2:30	#19:00-#20:30
9	17:30-19:10	9:30-11:10	3:30-5:10		17:30-19:00	9:30-11:00	3:30-5:00
	*1:00-*2:40	17:00-18:40	11:00-12:40		*1:00-*2:30	17:00-18:30	11:00-12:30
Impact Assessment				<b>Connected Vehicles</b>			
	10:50-12:15	2:50-4:15	#20:50-#22:15		10:40-12:05	2:40-4:05	#20:40-#22:05
	19:20-20:45	11:20-12:45	5:20-6:45		19:10-20:35	11:10-12:35	5:10-6:35
	*2:50-*4:15	18:50-20:15	12:50-14:15		*2:40-*4:05	18:40-20:05	12:40-14:05
Service and Business	Implementa	tion / FOTs		Safety Assurance			
Human Factors	13:15-15:10	5:15-7:10	#23:15-1:10		13:10-14:45	5:10-6:45	#23:10-0:45
	21:00-22:55	13:00-14:55	7:00-8:55		20:50-22:25	12:50-14:25	6:50-8:25
	*4:30-*6:25	20:30-22:25	14:30-16:25		*4:20-*5:55	20:20-21:55	14:20-15:55
Japanese Governmer	nt			Cybersecurity		Te la	
	15:25-16:40	7:25-8:40	1:25-2:40		15:00-16:15	7:00-8:15	1:00-2:15
	23:10-*0:25	15:10-16:25	9:10-10:25		22:40-23:55	14:40-15:55	8:40-9:55
	*6:40-*7:55	22:40-23:55	16:40-17:55	$( \land $	*6:10-*7:25	22:10-23:25	16:10-17:25
	_			Closing			
					16:15-16:20	8:15-8:20	2:15-2:20
					23:55-24:00	15:55-16:00	9:55-10:00
					*7:25-*7:30	23:25-23:30	17:25-17:30

\* The time will be the next day / # The time will be the previous day

All session are streamed 3 times

November 9 (Day I)				
(JST)	(CET)	(EST)		
9:00-10:40	1:00-2:40	#19:00-#20:40		
17:30-19:10	9:30-11:10	3:30-5:10		
*1:00-*2:40	17:00-18:40	11:00-12:40		
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# **Opening Session Regional Activities**

Opening Session	
Welcome Speech	Takayuki Kobayashi Minister of State for Science and Technology Policy Cabinet Office
	Kenneth M. Leonard Director Intelligent Transportation Systems Joint Program Office The United States Department of Transportation
Keynote Speech	Rosalinde van der Vlies Director Clean Planet Directorate, Directorate-General for Research and Innovation European Commission
	Seigo Kuzumaki Program Director for SIP-adus Fellow Advanced R&D and Engineering Company, Toyota Motor Corporation

November 9 (Day I)				
(JST)	(CET)	(EST)		
9:00-10:40	1:00-2:40	#19:00-#20:40		
17:30-19:10	9:30-11:10	3:30-5:10		
*1:00-*2:40	17:00-18:40	11:00-12:40		
All session are streamed 3 times * the next day / # previous day				

# **Opening Session Regional Activities**

#### Moderator : Manabu Umeda

Collaborative Research Coordinator for SIP-adus Project researcher, Mobility innovation collaborative research organization (UTmobI) The University of Tokyo

Regional Activities				
Session Abstract	In this session, speakers from each government like US, Europe, Japan, etc. will introduce latest research activities and topics regarding automated driving, including keynote speech from executives.			
Opening	Introduction for Regional Activities Session Moderator : Manabu Umeda			
Presentation	Overview of United States Department of Transportation Automated Driving Research	<b>Robert Heilman</b> Director, Office of the Assistant Secretary for Research and Technology The United States Department of Transportation		
	Connected, Cooperative and Automated Mobility – the EU perspective	Ludger Rogge Policy Officer, Directorate-General for Research and Innovation European Commission		
	Research on autonomous driving in Germany	Reinhold Friedrich Deputy Head of Division, Electronics and Autonomous Driving Federal Ministry of Education and Research		
	Development of ICV and Smart Mobility in China	Keqiang Li Professor, School of Vehicle and Mobility Tsinghua University		
Closing	Closing for Regional Activities Session	Moderator : Manabu Umeda		

SIP-adus Workshop 2021 Plenary Session Agenda November 9 (Day 1)					
(JST) (CET) (EST) 10:50-12:15 2:50-4:15 #20:50-#22:15 19:20-20:45 11:20-12:45 5:20-6:45 *2:50-*4:15 18:50-20:15 12:50-14:15 All session are streamed 3 times * the next day / * previous day					
Session Abstract Diffusion of automated driving vehicles (ADs) will help to reduce traffic accidents, alleviate traffic congestion, resolve the driver shortage, and resolve other social problems. On the other hand, ADs are necessary to be installed with adequate consent by people and society. In this session, experts will address views, issues and challenges related to social impact of AD technologies.					
Opening	Introduction for Impact Assessment Session Moderator : Takashi Oguchi				
	Analysis of automated driving diffusion : Diffusion paths into the German car market	Christian Winkler Head of Department, Institute of Transport Research German Aerospace Center (DLR)			
	Assessment of Socioeconomic Impacts of Automated Driving	Hiroaki Miyoshi Professor, Graduate School of Policy and Management Doshisha University			
Presentation	Social Acceptance of Automated Driving Empirical Insights and First Lessons	<b>Torsten Fleischer</b> Deputy Director Institute for Technology Assessment and Systems Analysis (ITAS) Karlsruhe Institute of Technology (KIT)			
	Social acceptance of Autonomous Vehicles A qualitative analysis of Japanese newspaper articles on AVs	Ayako Taniguchi Professor, Systems and Information Engineering University of Tsukuba			
	Using System Dynamics for Automated Vehicle Impact Assessment	Scott Smith Operations Research Analyst, Volpe Center The United States Department of Transportation			
Closing	Closing for Impact Assessment Session	Moderator : Takashi Oguchi			

### November 9 (Day 1)

(JST)	(CET)	(EST)
13:15-15:10	5:15-7:10	#23:15-1:10
21:00-22:55	13:00-14:55	7:00-8:55
*4:30-*6:25	20:30-22:25	14:30-16:25

#### All session are streamed 3 times \* the next day / \* previous day

## Service and Business Implementation / FOTs Human Factors

#### Moderator : Yurie Toyama

Researcher, Smart Region Division Mitsubishi Research Institute

#### Moderator : Satoshi Kitazaki

Director

Human-Centered Mobility Research Center (HCMRC) National Institute of Advanced Industrial Science and Technology (AIST)

Session Abstract	Service and Business Implementation / FOTs In this session, we will discuss how we can think about the feasible business model for automated driving and how to integrate autonomous driving into local transport.
	<b>Human Factors</b> Public transport services using automated shuttles and busses are expected to be a key solution to the social problem of limited mobility in rural areas and have been tested in fields in various countries. High level safety is essential for social implementation and wide spread of the services. In automated mobility services, both system and service are designable. The larger degree of freedom in design is expected to bring breakthroughs for the implementation but may raise new risks due to the complexity. In this session, human factor challenges for safety of the automated mobility services in various countries will be shared.

Speakers are listed on the next page

		DIP-duus			
November 9 (Day 1)					
(JST)	(CET)	(EST)			
13:15-15:10	5:15-7:10	#23:15-1:10			
21:00-22:55	13:00-14:55	7:00-8:55			
*4:30-*6:25	20:30-22:25	14:30-16:25			

SIP-adus Workshop 2021 Plenary Session Agenda Day 1) (EST) Service and Business 14:30-16:25 Human Factors Model Model Model Model Model Mational Institute of Mational I

#### Moderator : Yurie Toyama

Mitsubishi Research Institute

#### Moderator : Satoshi Kitazaki

National Institute of Advanced Industrial Science and Technology (AIST)

All session are streamed 3 times \* the next day / \* previous day

Opening	Introduction for the SBI/FOTs and HF session	Moderator : Yurie Toyama
	Shuttles - from early pilots to commercial deployment	Jan Hellåker Chairman Drive Sweden
	UNICARagil Disruptive Modular Architecture for Agile, Automated Vehicle Concepts	Lutz Eckstein Director, Institute for Automotive Engineering (ika) RWTH Aachen University
	HEAT - Hamburg Electric Autonomous Transportation	Katrin Schwager Project Manager, Innovation and Change Hamburger Hochbahn AG
Presentation	AIST's efforts toward social implementation of automated driving mobility services	Shin Kato Prime Senior Researcher, Human-Centered Mobility Research Center National Institute of Advanced Industrial Science and Technology (AIST)
	Automated Driving Systems for Rural America	Daniel McGehee Professor and Director, National Advanced Driving Simulator and Dept of Industrial and Systems Engineering, University of Iowa
	Automated Driving Systems	Timothy Haile   Executive Director, All Departments   Contra Costa Transportation Authority
	East Contra Costa County(ECCC) Dynamic Personal Micro Transit (DPMT) PROJECT	Habib Shamskhou President, Engineering/Program Management/Technology Facilitation Advanced Mobility Group
	INCLUSIVE DESIGN ACROSS THE TRAVEL CHAIN	Jordana Maisel Assistant Professor, Urban and Regional Planning University at Buffalo, State University of New York
Closing	Closing for the SBI/FOTs and HF session	Moderator : Satoshi Kitazaki

November 9 (Day 1)				
(JST)	(CET)	(EST)		
15:25-16:40	7:25-8:40	1:25-2:40		
23:10-*0:25	15:10-16:25	9:10-10:25		

\*6:40-\*7:55

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## **Japanese Government**

22:40-23:55 All session are streamed 3 times \* the next day / \* previous day

16:40-17:55

In this session, their various attempts related to automated driving, ITS as well as Information and Communication **Session Abstract** technologies will be introduced by the contributing Japanese government ministries and agencies.

ntation	National Research Project on Automated Driving to Realize Society 5.0 - SIP-adus in Japan -	<b>Chie Fukushima</b> Director for SIP-adus, Secretariat of Science, Technology and Innovation Policy Cabinet Office
	Public-Private ITS Initiative / Roadmaps Past initiatives and the basic concept of the future ITS Initiative	Takahiro Suzuki Senior Planning Officer Digital Agency
	Police Efforts toward Realization of Automated Driving	Kenichi Ito Director, Automated Driving Planning Office National Police Agency
	MIC's Initiatives for Automated Driving Society	<b>Shinji Ide</b> Director of the New Generation Mobile Communications Office Radio Department, Telecommunication Bureau Ministry of Internal Affairs and Communications
	METI's effort to realizing autonomous driving	Shigekazu Fukunaga Director, ITS and Autonomous Driving Promotion Office Automobile Division, Manufacturing Industries Bureau Ministry of Economy, Trade and Industry
	Automated Driving Services in Rural Areas	Koichi Sakai Director, ITS Policy and Program Office Ministry of Land, Infrastructure, Transport and Tourism
	Efforts of Road Transport Bureau, MLIT For the Realization of Automated Driving	Yoshitaka Tada Director, Policy planning office for Automated Driving Technology Engineering and Environmental Policy Division Road Transport Bureau

Ministry of Land, Infrastructure, Transport and Tourism

	SIP-adus Workshop 2021 Ple	enary Session Agenda	
	• 10 (Day 2) CET) (EST)		
<b>9:00-10:30</b> 1 17:30-19:00 <b>9:3</b> *1:00-*2:30 17:0	:00-2:30 #19:00-#20:30 <b>0-11:00</b> 3:30-5:00 00-18:30 <b>11:00-12:30</b> <b>times</b> * the next day / * previous day	Map Visiting Researcher Center for Spatial Information Science The University of Tokyo	
Session Abstract	This session is to share the world latest examples of dynar updates, and to discuss the direction for further internation technologies.	nic contents distribution/exchange with Dynamic Map and the nal collaborations and the possibility for the utilization of latest	
Opening	Introduction for Dynamic Map Session Moderator : Satoru Nakajo		
Presentation	ADASIS and SENSORIS	Jean-Charles Pandazis ADASIS & SENSORIS coordinator, Innovation & Deployment European Road Transport Telematics Implementation Coordination Organisation-Intelligent Transport Systems & Services Europe (ERTICO-ITS Europe)	
	OADF – status update	Andras Csepinszky Speaker, Steering Committee Open Auto Drive Forum	
	Fully automated mobility with location intelligence	Akihiro Takahashi VP Sales & Japan Country Manager, Sales HERE Technologies	
	Dynamic Map Platform Co. Current Initiatives and Future Developments	Hiroyuki Inahata Representative Director,President Dynamic Map Platform Co., Ltd.	
	FOTs in the Tokyo Waterfront area FY2019 to 2020 Results and Overview of Implementation in FY2021	Yoshiaki Tsuda Chief Engineer, Spatial Information Systems Engineering Section/Information Technology Systems Department KAMAKURA WORKS, MITSUBISHI ELECTRIC CORPORATION	
Closing	Closing for Dynamic Map Session	Moderator : Satoru Nakajo	

### November 10 (Day 2)

(JST)	(CET)	(EST)
10:40-12:05	2:40-4:05	#20:40-#22:05
19:10-20:35	11:10-12:35	5:10-6:3
*2:40-*4:05	18:40-20:05	12:40-14:05

## **Connected Vehicles**

#### Moderator : Norifumi Ogawa

Staff Manager, Technical Research Dept. Mazda Motor Corporation

All session are streamed 3 times \* the next day / # previous day

Session Abstract	The use of connectivity for automated driving and Advanced Safe Driving Systems is being considered in each regions of the world, but it has not yet been put into full-scale practical use. We will share trends regarding cooperative driving automation in each region and consider issues.		
Opening	Introduction for Connected Vehicles Session Moderator : Norifumi Ogawa		
Presentation	Trends in US V2X and Cooperative Automation	John Kenney Director, InfoTech Labs Toyota Motor North America	
	V2X FOR TRANSPORTATION SAFETY	<b>Tom Schaffnit</b> Operations Research Analyst, Volpe National Transportation Systems Center The United States Department of Transportation	
	C-ITS in Europe	Niels Peter Skov Andersen CEO Anemone Technology	
	C-ITS THE EUROPEAN INFRASTRACTURE IS PREPARED TO SUPPRT CONNECTED VEICLES	Martin Boehm Technical Director AustriaTech - Federal Agency for technological Measures Ltd.	
	SIP-adus FOTs in Tokyo waterfront area - Toward the realization of cooperative autonomous driving-	Masato Minakata Grand Master, R&D and Engineering Management Div. Toyota Motor Corporation	
	Research of V2X communication for Cooperative Driving Automation	Norifumi Ogawa Staff Manager, Technical Research Dept. Mazda Motor Corporation	
Closing	Closing for Connected Vehicles Session Moderator : Norifumi Ogawa		

	SIP-adus Workshop 2021 Ple	nary Session Agenda
November	10 (Day 2)	
(JST)(13:10-14:45520:50-22:2512:5*4:20-*5:5520:1	CET) (EST) :10-6:45 #23:10-0:45 Safety Assi	Urance Automated Driving & Advanced Safety System Development Toyota Motor Corporation
Session Abstract	The virtual environment is an indispensable technology for virtual testing technology for safety assurance, the internat environment and the method of validation should be enhar discussed in this session in order to figure out how to proce	nced. The virtual environment and evaluation methods are
Opening	Introduction for Safety Assurance Session Moderator : Satoshi Taniguchi	
Presentation	We make AUTONOMOUS MOBILITY happen.	Frank Gruson Head of Advanced Engineering Radar. Radar Concept Development Continental / ADC Automotive Distance Control Systems GmbH
	Simulation toolchain for safety assurance with focus on automotive radar	Matthias Hein Director, Thuringian Center of Innovation in Mobility Technische Universitat Ilmenau
	Driving Intelligence Validation Platform for Automated Driving Safety Assurance	Hideo Inoue Director, Advanced Vehicle Research Institute Kanagawa Institute of Technology
	A scenario database linked to a virtual platform for automated driving safety development and evaluation purposes	Jacobo Antona-Makoshi Senior researcher and Group manager, Autonomous Driving Research Department, Japan Automobile Research Institute
	VVM - Towards a comprehensive framework for AD safety assurance	Roland Galbas Project Lead, ADAS System Development Robert Bosch GmbH
	An Overview of the Safety Case Framework	Chan Lieu Senior Manager, Safety Policy Aurora
Closing	Closing for Safety Assurance Session	Moderator : Satoshi Taniguchi

SIP-adus Workshop 2021 Plenary Session Agenda			
Novembei	r 10 (Day 2)		
	(EST)		
	:00-8:15 1:00-2:15 <b>Cybersec</b>	UTITY Moderator : Shigeru Uehara Chair of Governing Board, J-Auto-ISAC	
22:40-23:55 <b>14:4</b> *6:10-*7:25 22:	<b>0-15:55</b> 8:40-9:55 <b>16:10-17:25</b>	Project General Manager, E/E Architecture Development Div., Toyota Motor Corporation	
	3 times * the next day / * previous day		
Session AbstractIt is expected that UN regulation will soon be adopted to detect and respond to cyber attacks, but it is not easy for each OEM to determine and implement the optimum detection performance level for their communication system. In this research, focusing on in-vehicle IDS / IDPS, we will consider the evaluation method for selecting the optimum IDS/IDPS for each OEM's communication system, technical requirements for the initial response/recovery action when cyber attacks detected and the basic thought of establishing V-SOC which can be said to be a competitive area for each OEM.			
Opening	Introduction for Cybersecurity Session	Moderator : Shigeru Uehara	
	Building VSOC in a connected ECO system of IDS and threat intelligence	Nishant Khadria Director, Cyber Emerging Technologies Deloitte	
Presentation	New Cyberattack and Proactive Survey Methodologies for Automotive Industry   Shinichi Kan Associate, Technology Consulting PwC Consulting Japan		
	Implementation of Cybersecurity Regulation - Requirements to IDS -	Shigeyuki Kawana Chair, Electronics Platform sub-committee Japan Automobile Manufacturers Association, Inc.	
	Misbehavior Detection and Prevention in Connected, Automated Driving	Frank Kargl University Professor, Institute of Distributed Systems Ulm University	
	Novel Capabilities Required for Intrusion Detection Systems for Automated Driving Vehicles	<b>Tsutomu Matsumoto</b> Professor, Faculty of Environment and Information Sciences Yokohama National University	
Closing	Closing for Cybersecurity Session	Moderator : Shigeru Uehara	

			Workshop 2021 Plenary Session Agenda
November	<sup>-</sup> 10 (Day	2)	
(JST) (	CET)	(EST)	
<b>16:15-16:20</b> 8	:15-8:20 2	2:15-2:20	Closing
23:55-24:00 <b>15:5</b>	<b>5-16:00</b> 9:	:55-10:00	
*7:25-*7:30 23:2	25-23:30 <b>17:</b>	25-17:30	
All session are streamed 3	times * the next day	y / <sup>#</sup> previous day	
Closing Remarks Chie Fukushima Director for SIP-adus, Secretariat of Science, Technology and Innovation Policy Cabinet Office			